# Power Systems Hardware-in-the-Loop Laboratory Testbed and Open Platform (HILLTOP)

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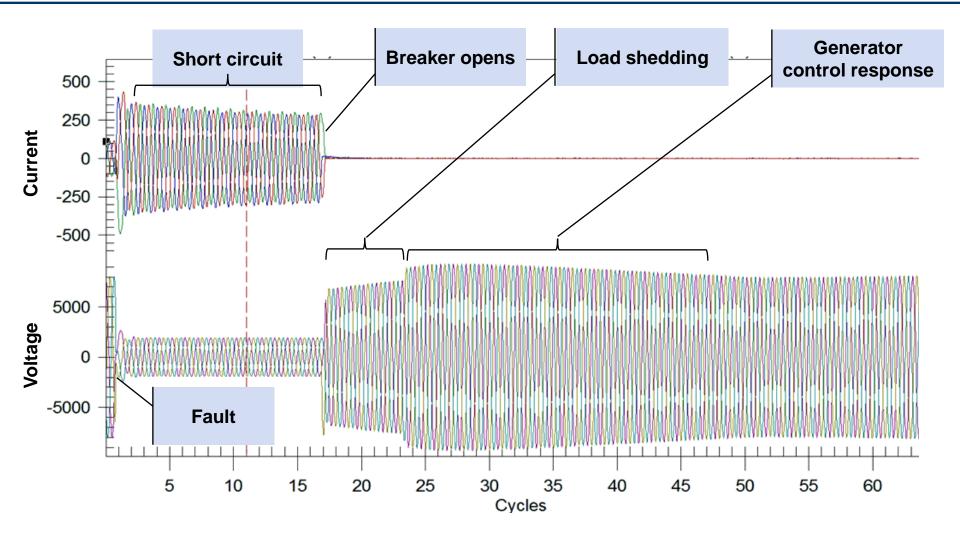
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Data capture: Scott Manson, SEL

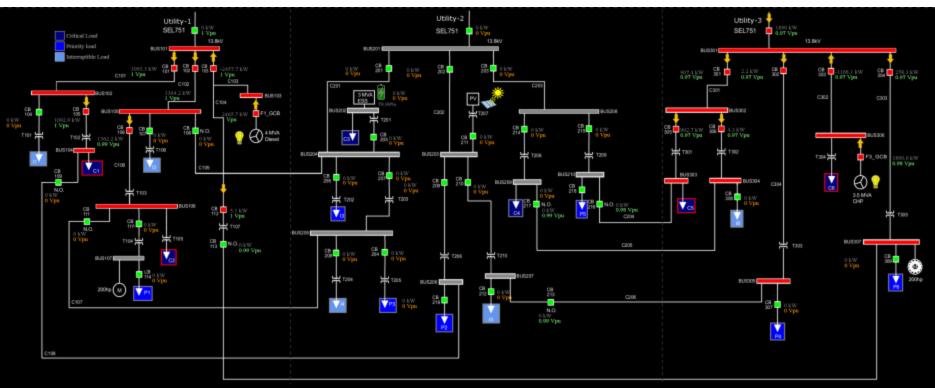
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## **Microgrid Test Feeders**





*Emergent behavior* is behavior of a system that does not depend on its individual parts, but on their relationships to one another. Thus emergent behavior cannot be predicted by examination of a system's individual parts. It can only be predicted, managed, or controlled by understanding the parts and their relationships.

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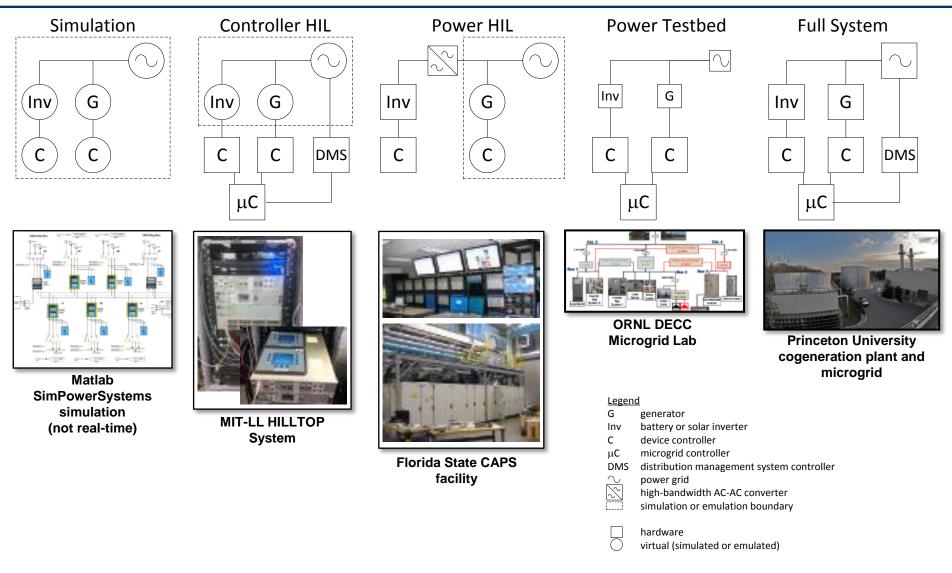
- High NRE for each project
  - One vendor's microgrid controller quote: \$1M starting price
- "Vaporware"
  - No standard list of functions or performance criteria
  - Difficult to validate marketing claims
- Risk of damage to expensive equipment
  - One utility-deployed microgrid: 1 year of controls testing, damaged a 750 kW transformer, required significant engineering staff support
- Interconnection behavior unknowable to utility engineers
  - Controls are implemented in proprietary software
  - Microgrids are a system of systems: Exhibit emergent behavior
- No standards verification
  - IEEE P2030.7 and P2030.8 standards are on the horizon

Need to reduce integration time, cost, & risk



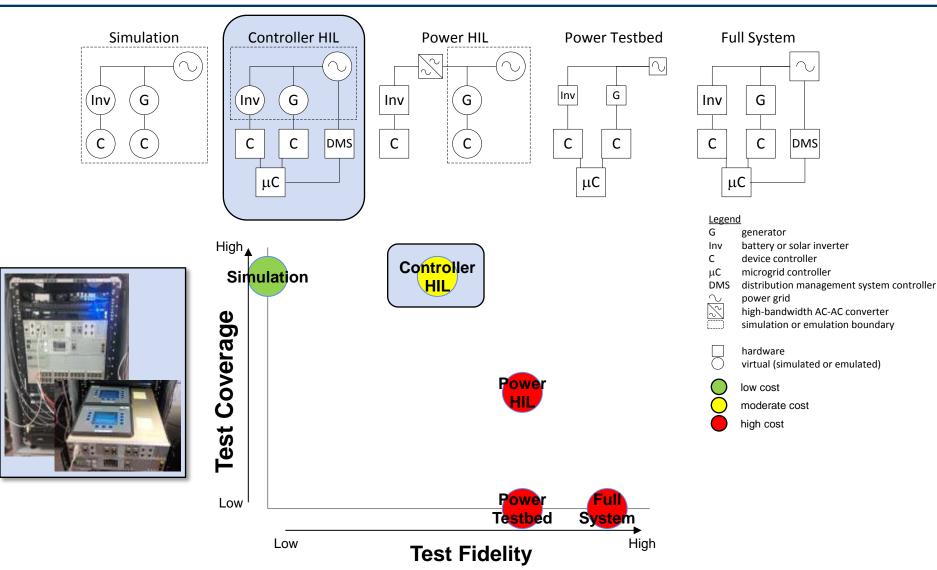
## **Types of Power System Testbeds**







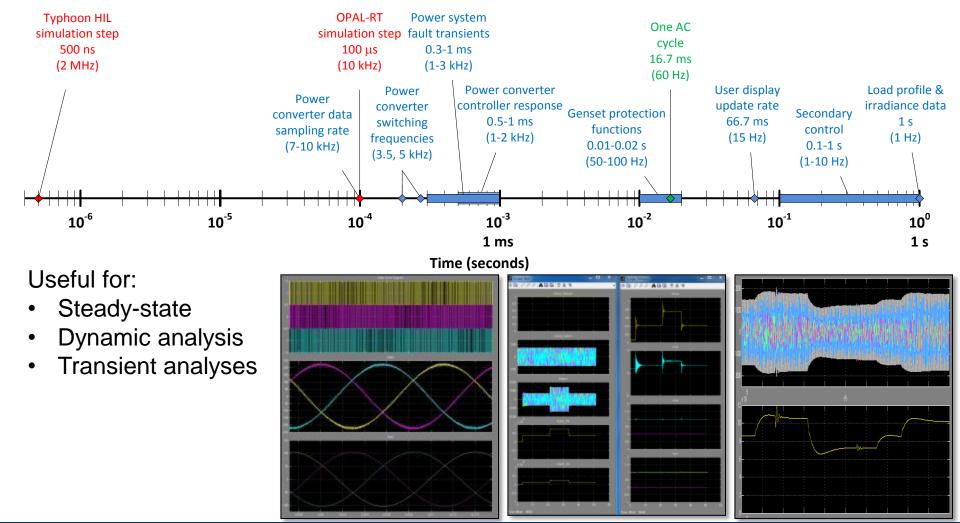




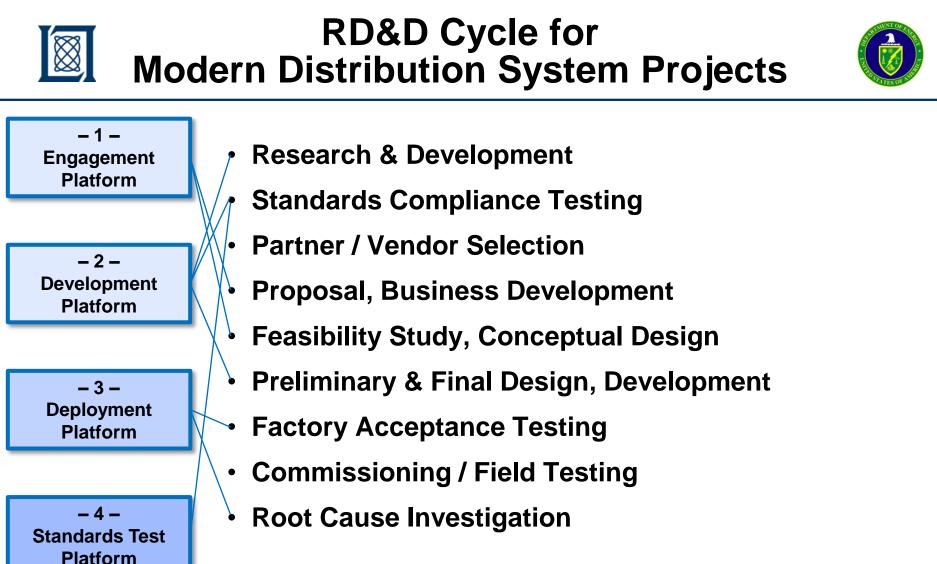




#### Microgrid controller HIL simulates in real-time at sub-cycle timescales



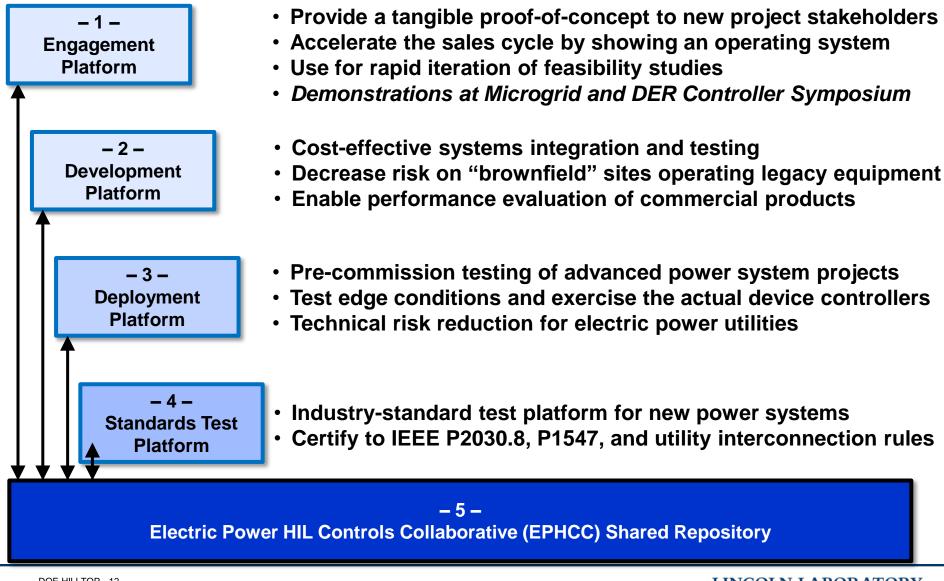
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## Vision for Power Systems HILLTOP







## Improvements Since Previous Symposium



Category	Improvement Since 1 <sup>st</sup> Symposium	
Real-time test platforms & microgrid controllers	2x	
Ported simulation environments	5x	
Physical device controllers	4x	
Test feeders	3х	
Test cases	4x	

Total	1000x
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In other words	+60 dB
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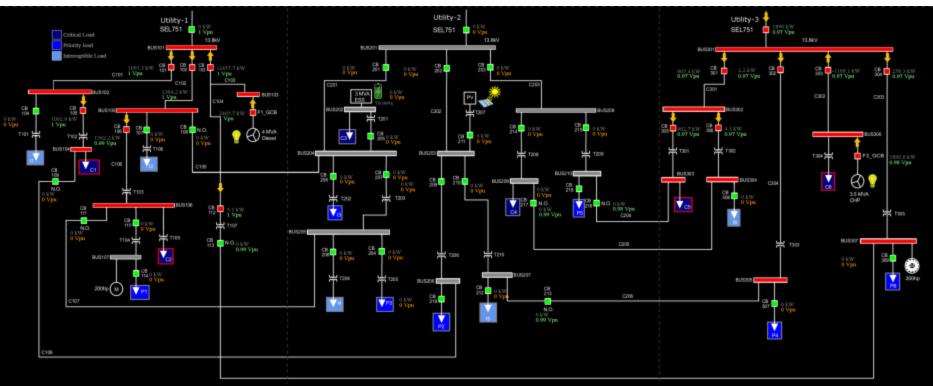


- Motivation
- Testbed Buildup
  - Integration Process
  - Demonstration Orientation



## **Test Feeders**





Representative of a community microgrid [

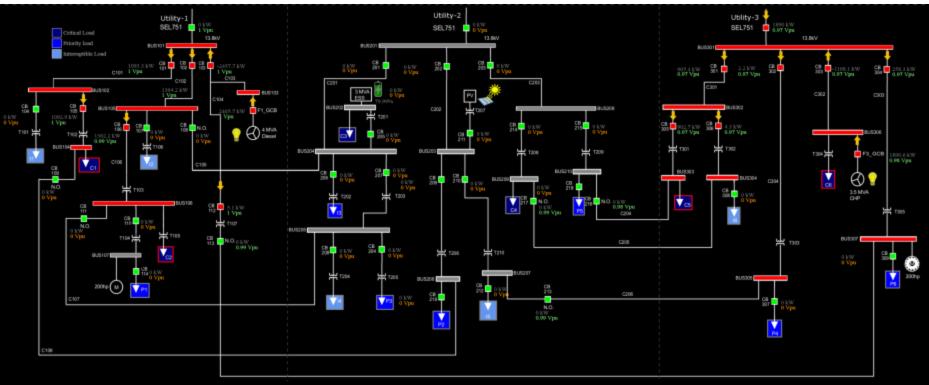
- Supports thorough controller evaluation
  - Multiple reconfigurations possible
  - Multiple interconnections to the utility
  - Insufficient generation when islanded

Peak demand	14 MW	
Available generation	10 MW	
Software components	100+	
DERs	5	
Relays	~50	



## Test System Segmentation for Real-time Simulation





- 3 cores: One per feeder + machine models
- 3 cores: Relay models for each feeder + UDP communications
- 1 core: Storage & PV power electronics models
- 1 core: Utility substation + high-speed data collection



## HILLTOP Rack #1 Using OPAL-RT Simulator





- Real-time target with Xeon Intel® Processor
  - Using 8 of 12 cores
  - 2.7 to 3.2 GHz

- FPGA-based I/O management with
  - Xilinx Spartan-3



## HILLTOP Testbed #2 Using Typhoon HIL Simulator

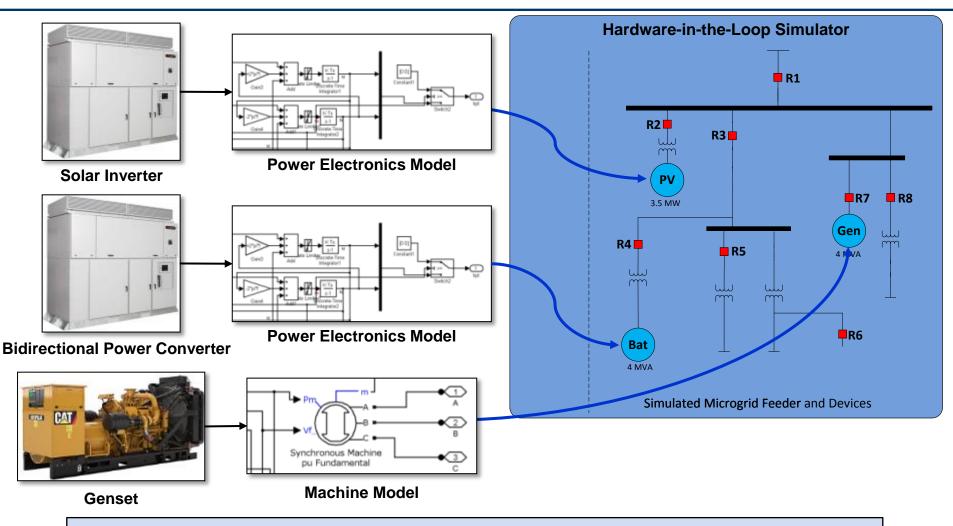


- HIL603 real-time simulator SEL HILConnect Woodward HILConnect **EPC HILConnect (PV** and ESS)
- 4 HIL603 units
  - High speed serial link interconnection 8 lane - 5GHz
- 2µs & 4µs time steps
  - Multirate electrical simulation
- 23 cores used
- 20ns digital sampling
- 42 simulated relays with Modbus comms
  - 1.2 ms execution rate



#### Add Machine and Power Electronics Models



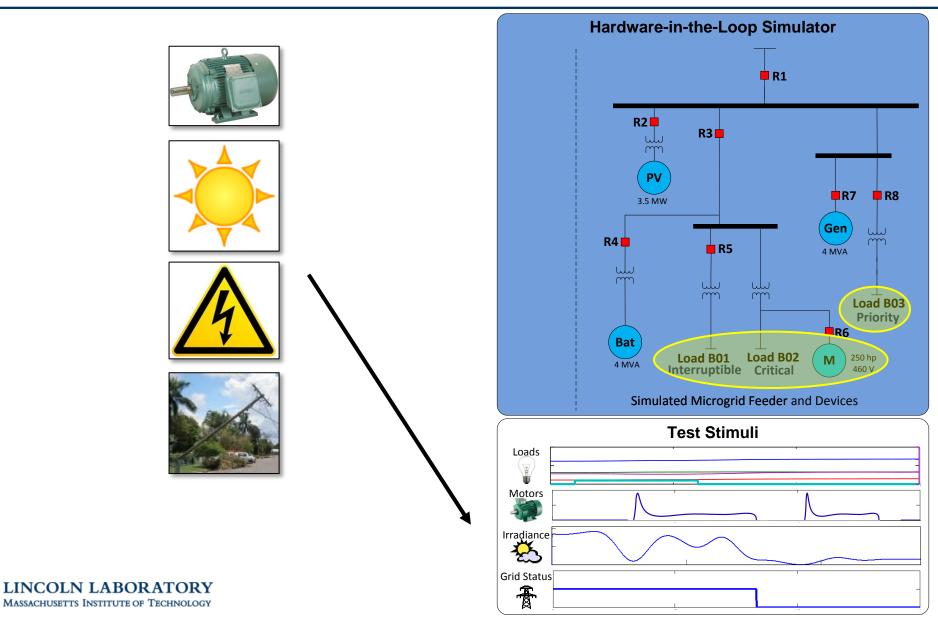


Create detailed models of the DER devices



## Assign Load Priorities, Add Test Stimuli





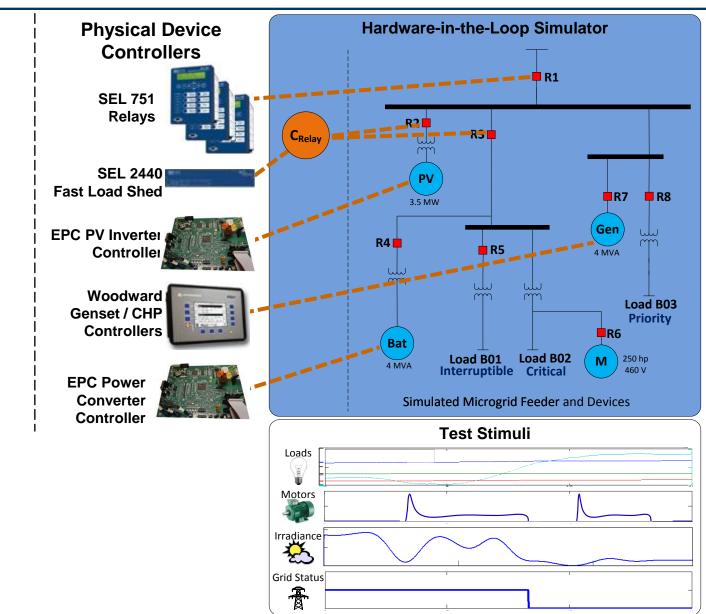


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## Add Commercial Controllers as Hardware-in-the-Loop

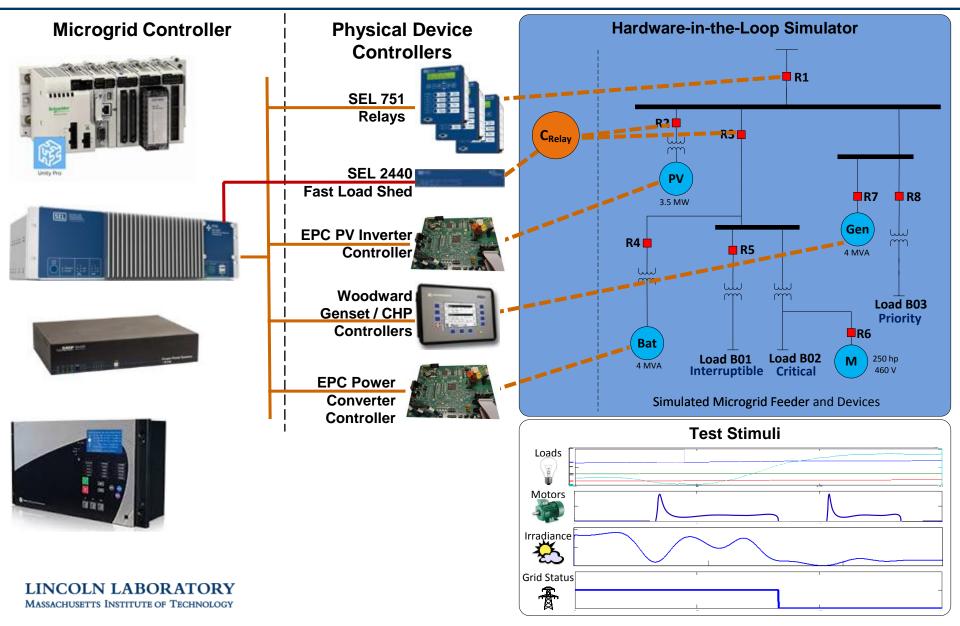






## **Integrate Microgrid Controllers**

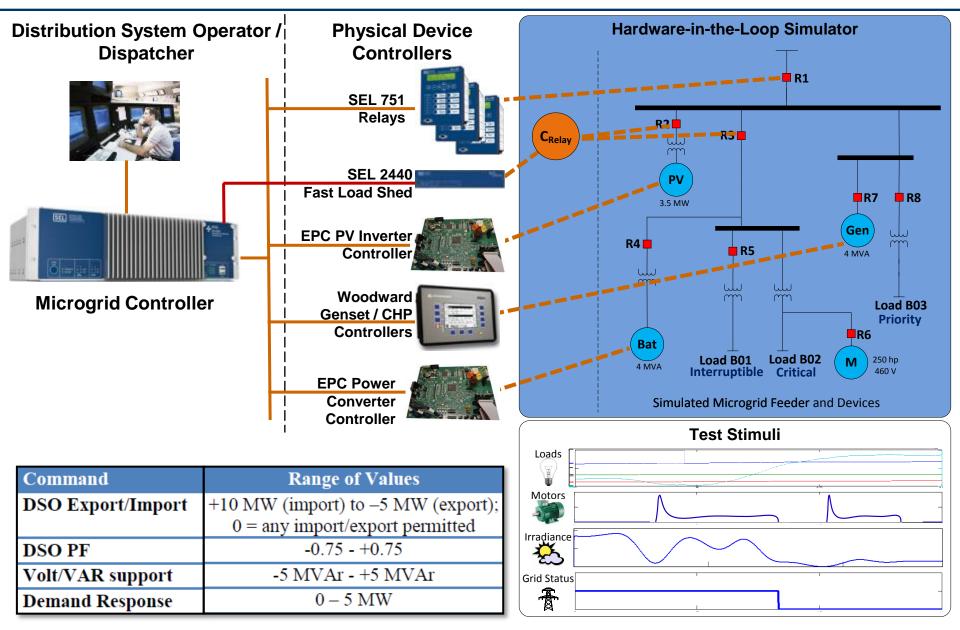






## **Integrate Microgrid Controllers**







## **Simulated Diesel Genset Block**

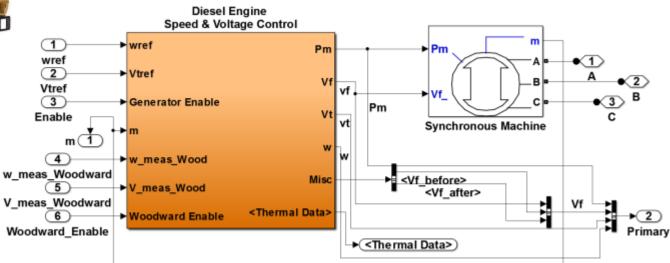






	1 MW Genset	4 MW Genset
Manufacturer / Model	CAT C32	CAT C175-20
Rating (kVA)	1,000	4,000
<b>Power Factor</b>	TBD	TBD
Voltage (V)	480	13,800
Frequency (Hz)	60	60
Speed (RPM)	1800	1800
Minimum Output Power	25kW	100kW
Startup Time	<10 sec	<15 sec

#### Genset ratings and characteristics



Synchronous Machine, Governor, and AVR Models

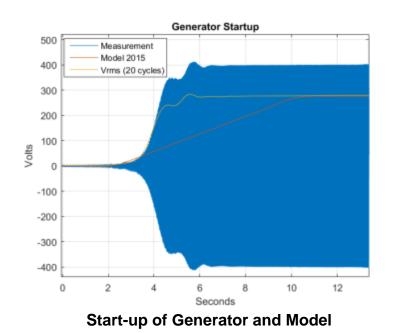


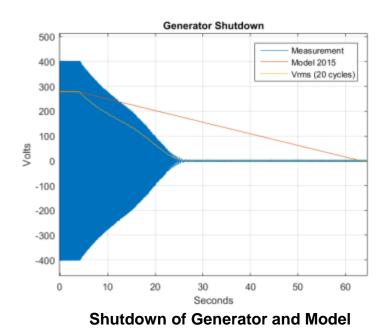




- 1 MVA
- 480Vac
- 3 phase

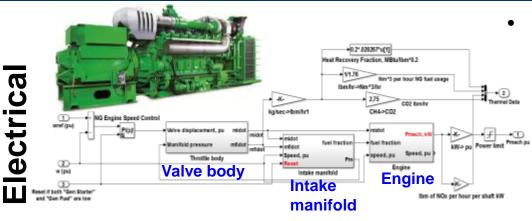
- Generator statistics
- High speed instrumentation
  - 8kHz sampling
  - Voltage and current
  - Bias signals



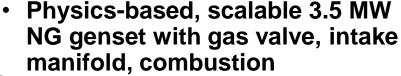




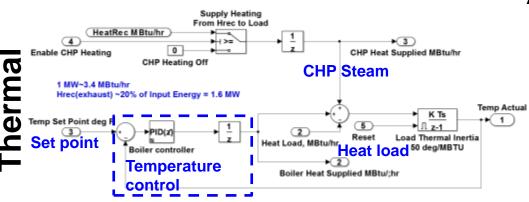
## **Natural Gas Combined Heat and Power**



GE/Jenbacher J620 NG Engine (1800 RPM) 3.5 MW Natural Gas Engine Model (Physics Based)



- Fuel usage
- GHG emissions
- Heat recovery
- Woodward easYgen 3500 compatible



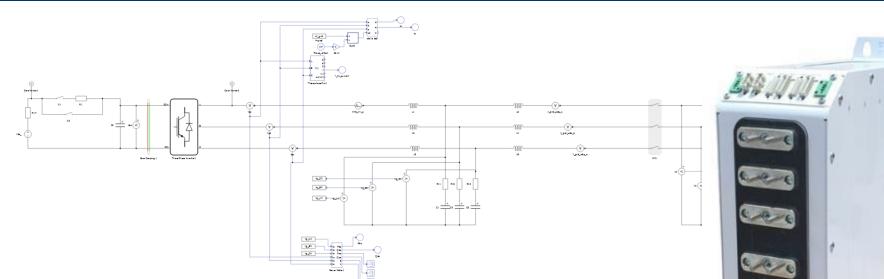
- Aggregate CHP system model
  - Modbus commanded heating or cooling mode, temperature set-point
  - Independent heat load input
  - Parametrically settable losses, cooling coefficient of performance, thermal inertia

#### **CHP Aggregate Thermal Model**



## EPC Power Electronics Models: Solar PV and Energy Storage System





- 4-quadrant control module
- Control capabilities for microgrid operation
  - Real (P) and Reactive (Q) power dispatch
  - Voltage islanding mode
  - UPS parallel backup mode
- Manufacturer validated inverter model
- Modbus over RS485 Communication





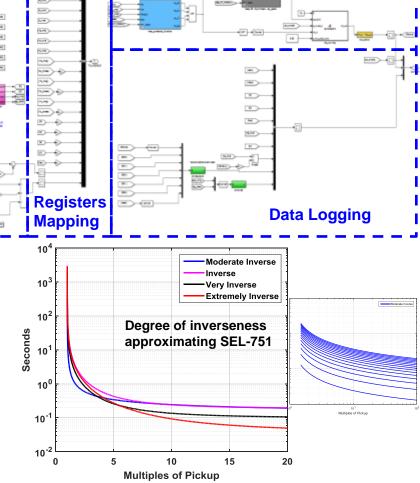
## **Generic Software Relay**



Protection Functions

- Used for telemetry
  Various time current characteristic curves (TCC)
  Active protection features:

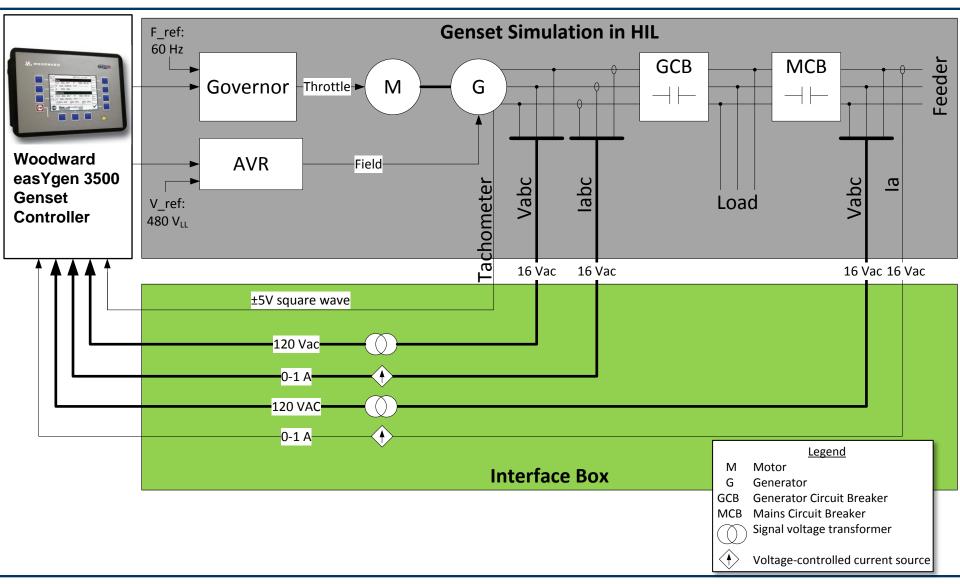
  Overcurrent (50, 51)
  Over/under voltage (27, 59)
  Synchronism check (25)
  Reclosing (79)
- Modbus TCP interface
- Multiple protection group settings
   accessible by the microgrid controller
  - Grid-tied protection
  - Islanded protection





#### Device Controller Integration: Woodward easYgen 3500

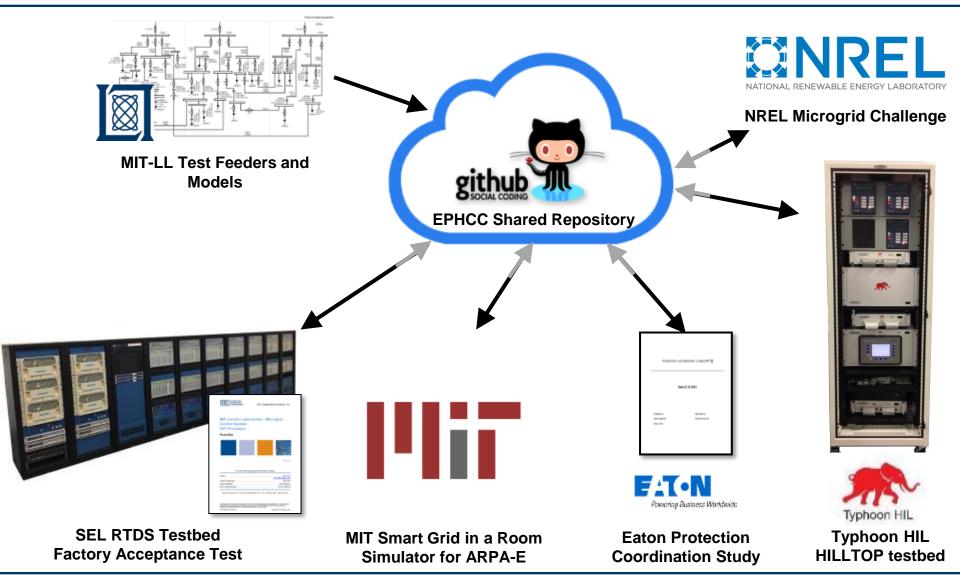






## **Models Ported to Numerous Platforms**

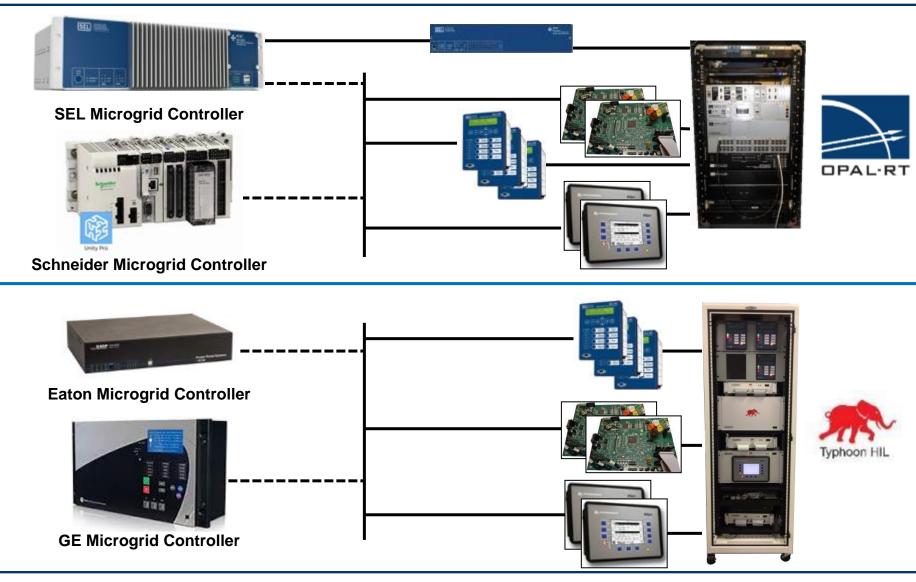






## Today: HILLTOP on 2 Real-time Sims Operating 4 Microgrid Controllers





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- Motivation
- Testbed Buildup
- Integration Process
  - Demonstration Orientation



## The Integration Process: Device Integration



- I/O point check
- Communications
  - Comm w/out errors, change setpoints, scale factors
- Device-level performance characterization
  - Load acceptance, load rejection tests
  - Large setpoint changes
  - Determine capability curves
- Customize site-specific controls / DER mode changes
- DER paralleling / generator load sharing



## The Integration Process: Microgrid Controller Configuration



- Transitions
  - Intentional islanding
  - Unplanned islanding
  - Synchronization and reconnection
- Steady-state operation
  - Grid-tied optimal dispatch
  - Islanded stability
- Faults
  - Protection
  - Reconfiguration for critical load service





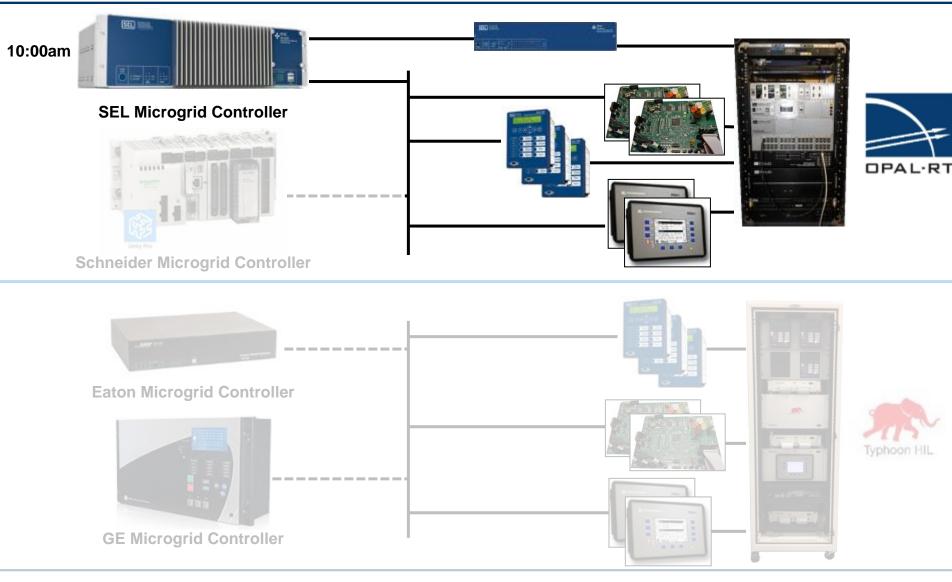


- Motivation
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#### **Demo #1: SEL Controller on OPAL-RT** Focus: Black Start, Islanding, & Fast Load Shedding





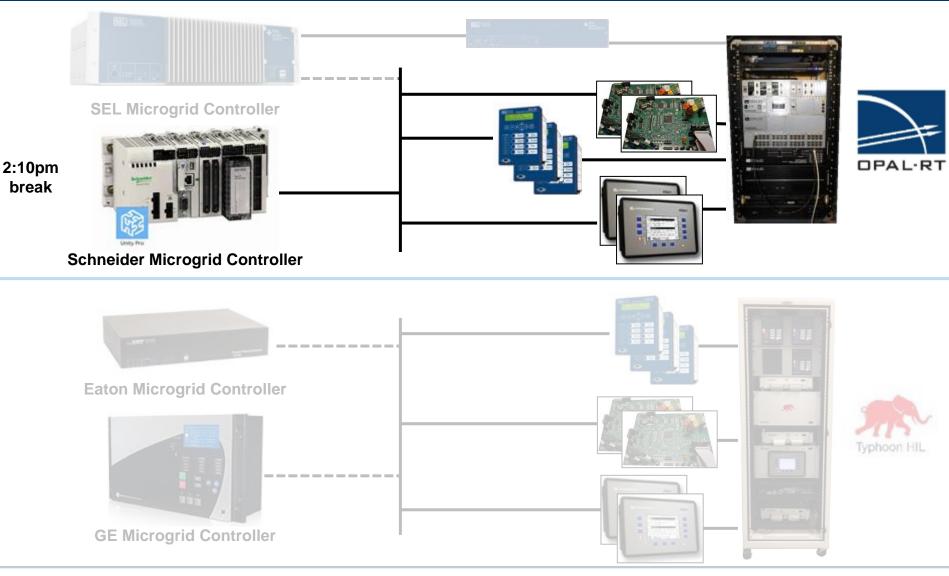
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## #3: Schneider on OPAL-RT

#### **Focus: Reconfiguration & Load Prioritization**



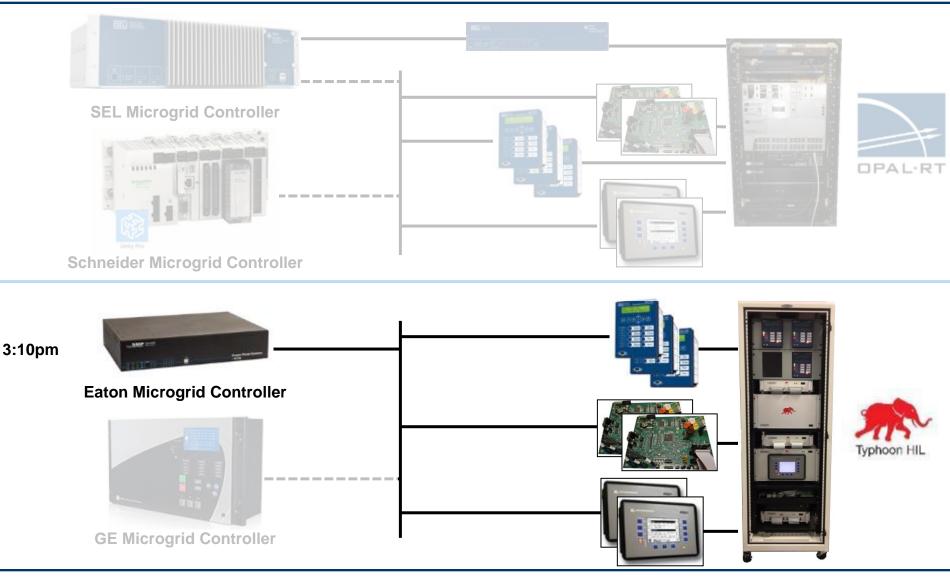




## #4: Eaton Controller on Typhoon HIL

**Focus: Protection & DER Dispatch** 



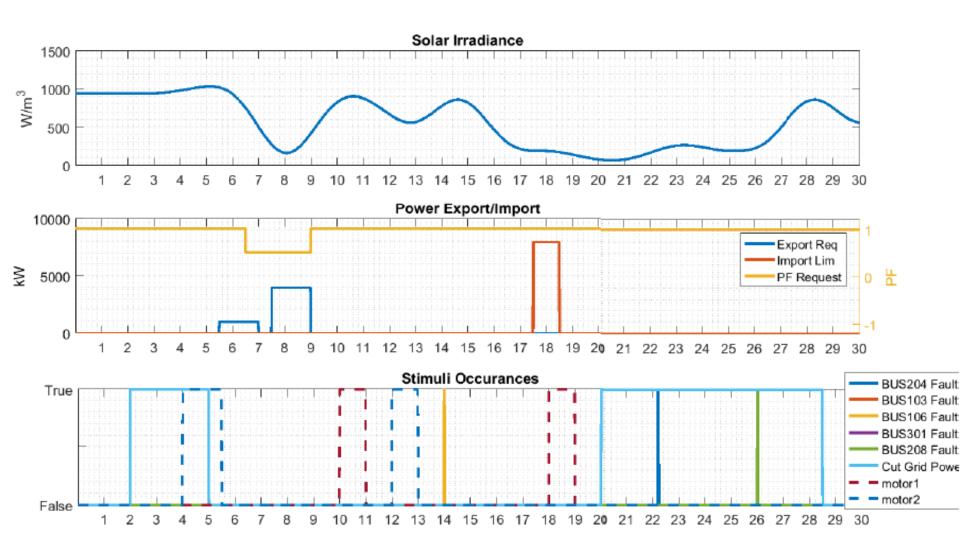


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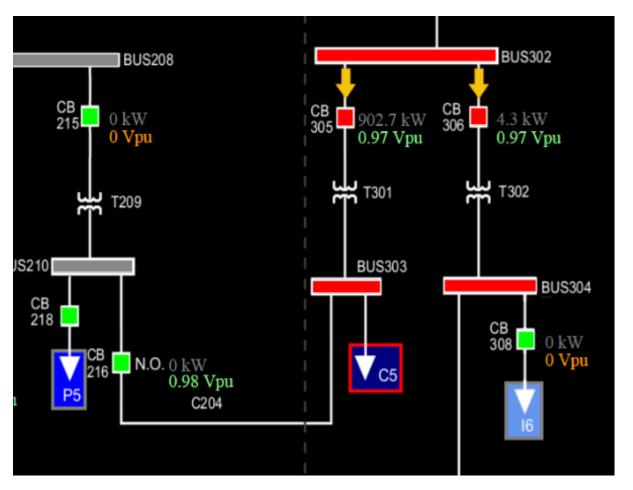


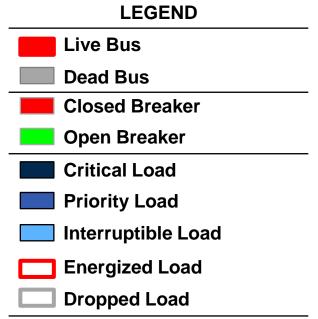










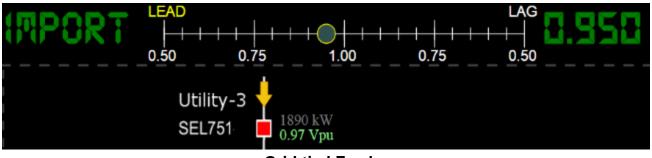




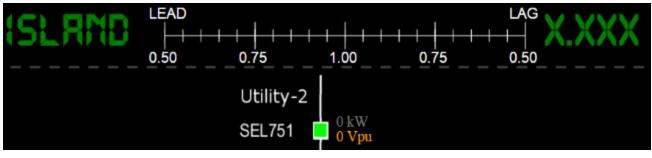
Energized Motor Load







**Grid-tied Feeder** 

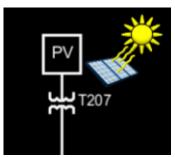


**Islanded Feeder** 

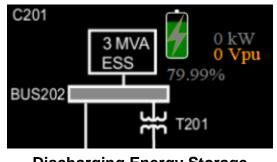


## **Distributed Energy Resources**

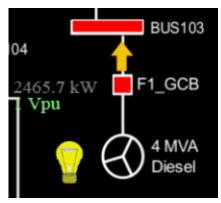




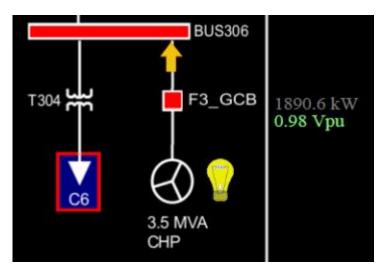
Energized Solar PV Array



Discharging Energy Storage System (ESS) / Battery



**Energized Diesel Genset** 

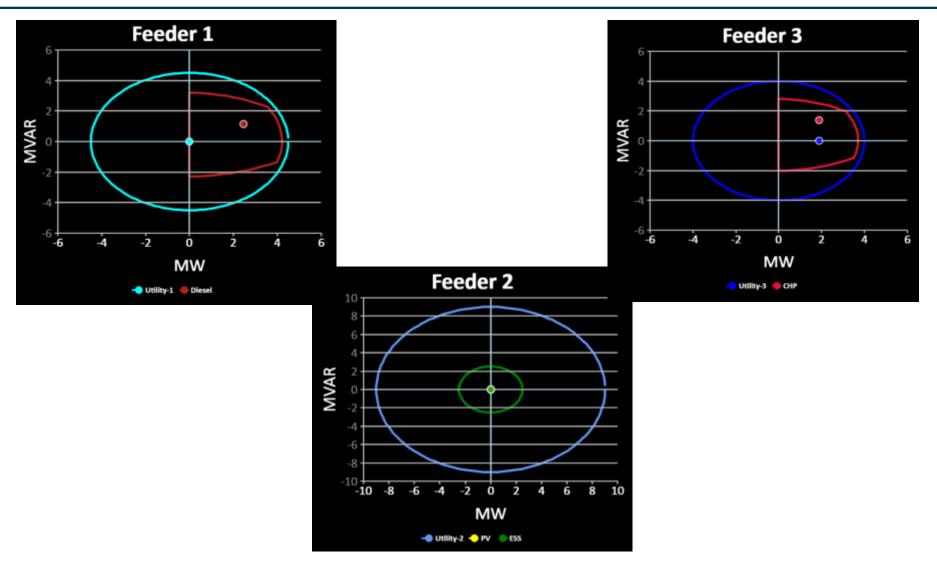


Energized Natural Gas-fired Combined Heat and Power (CHP) Plant



#### Real and Reactive Power Production and Capability Curves

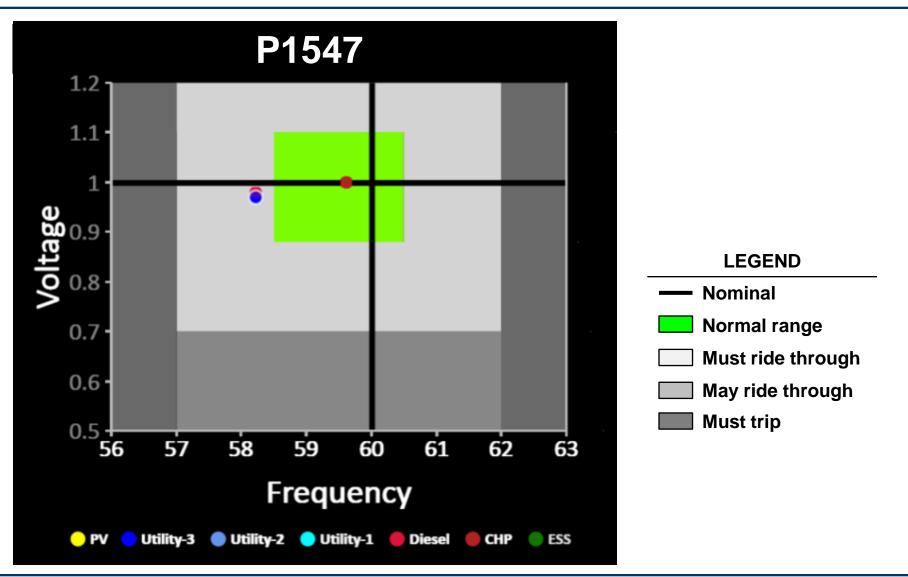






#### Testing of Future Advanced DER: IEEE P1547 Draft Amendment

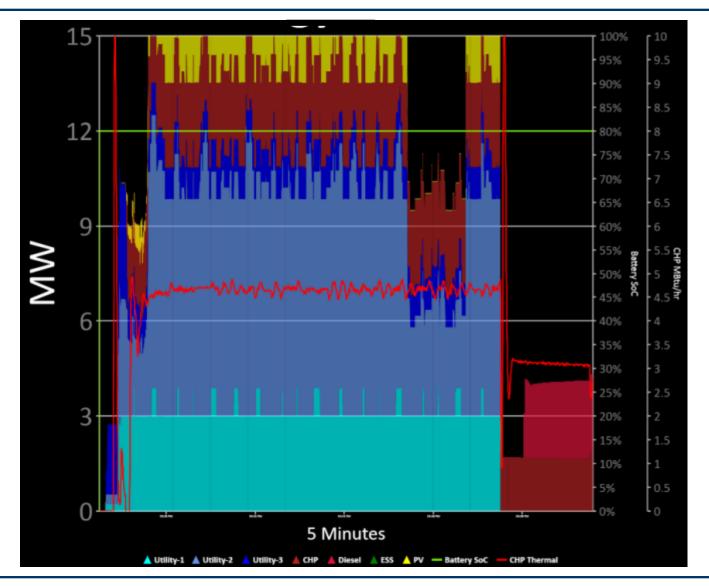






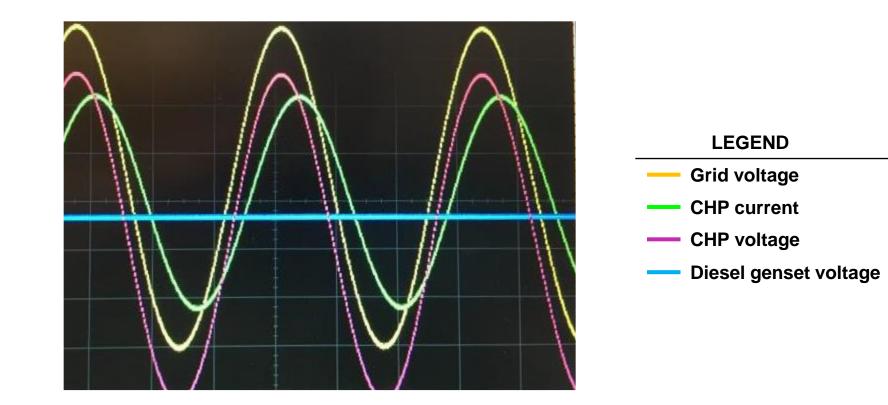
### **Energy Sources "Sand Chart"**







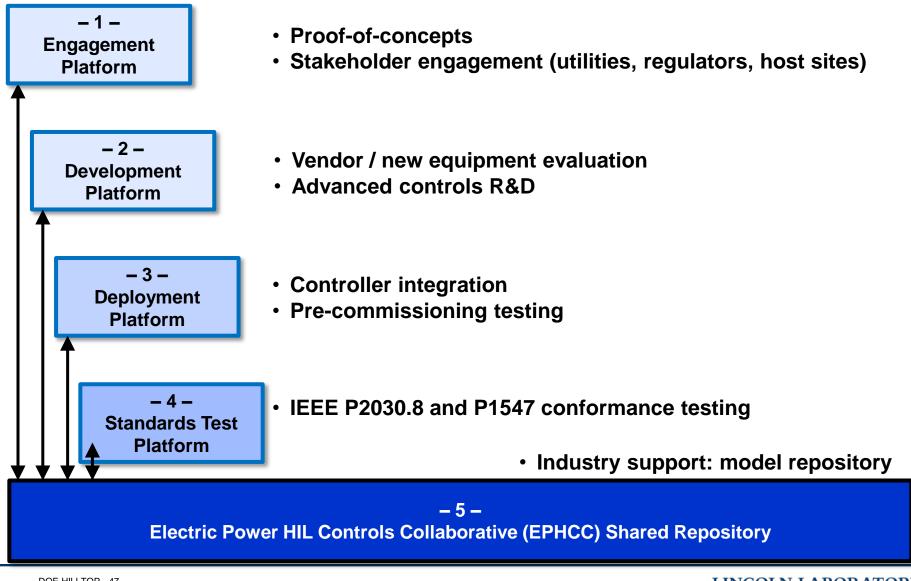






#### Our Mission: Transitioning Technology for National Energy Resilience







#### Acknowledgements



#### **Sponsor**

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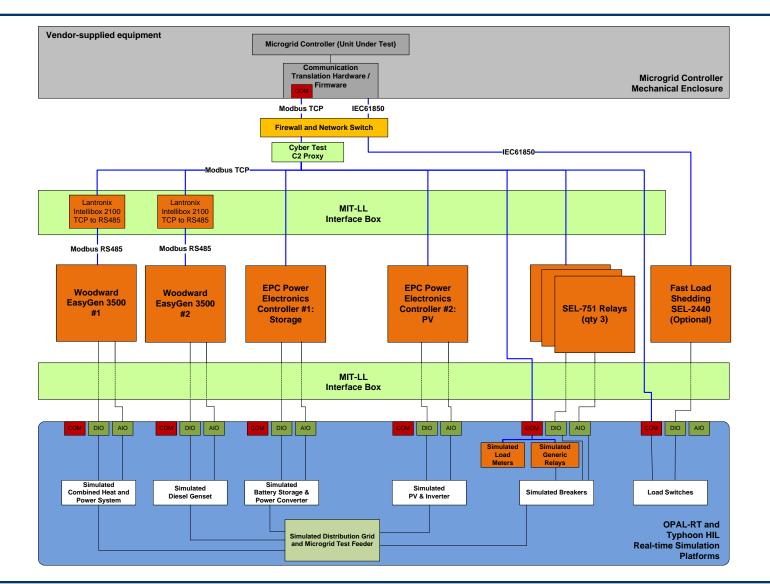




# BACKUP



## **HIL Platform Block Diagram**



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