

# Research Challenges for the Next Decade

18 September 2007

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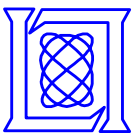
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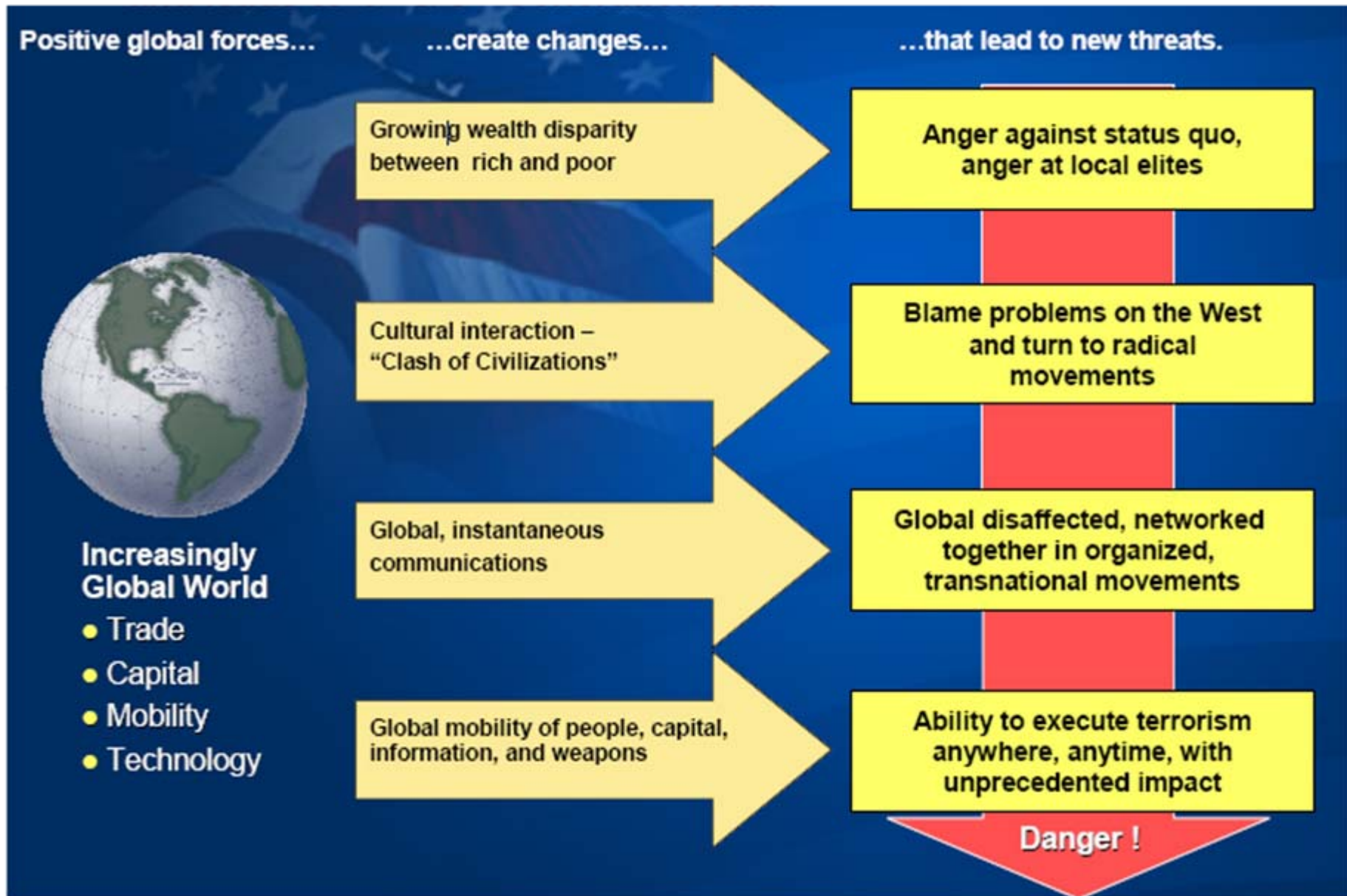
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# A New World has Emerged in the Last Decade

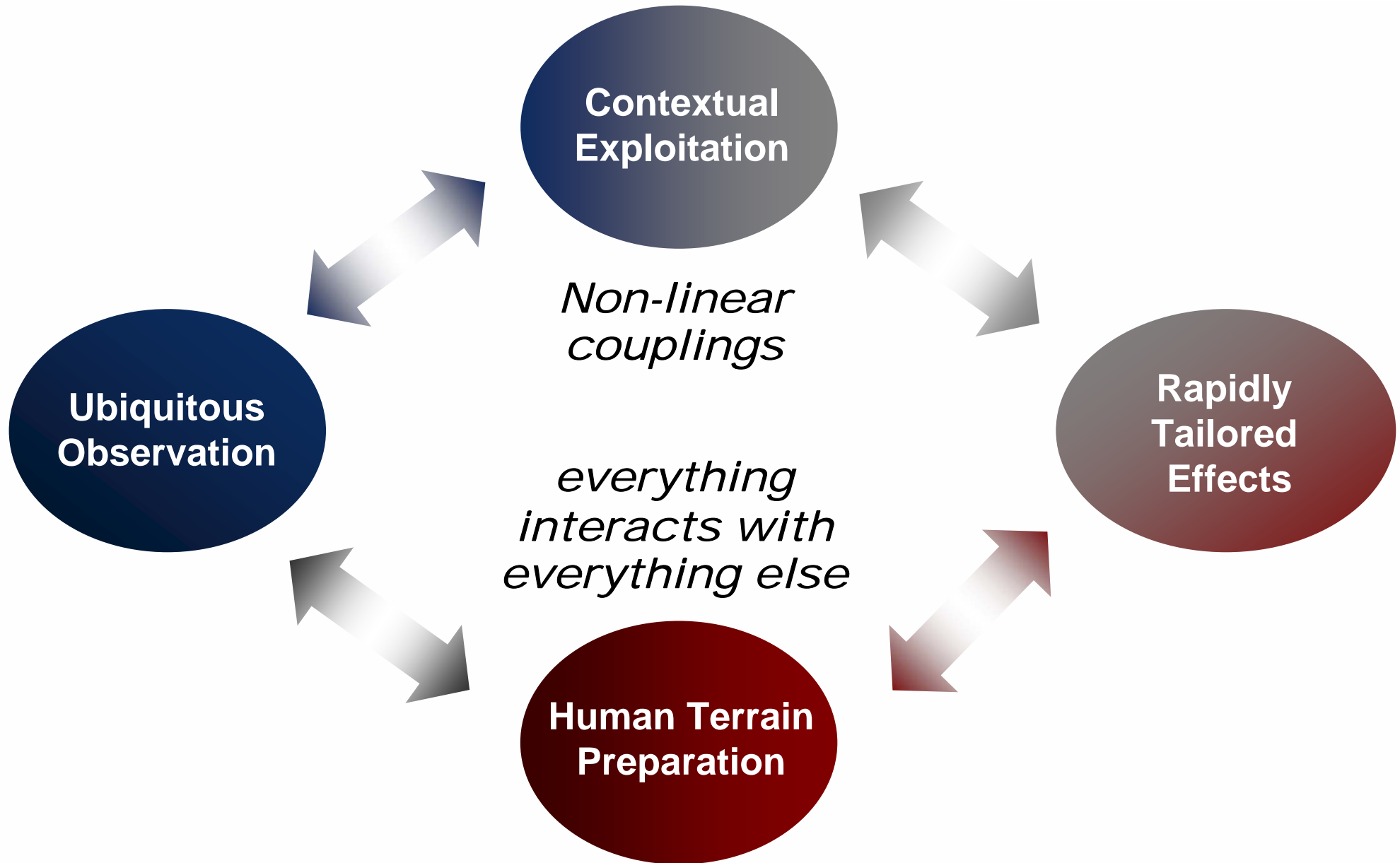


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# THE FOUR BROAD CAPABILITY CATEGORIES – AN OODA-LIKE LOOP FOR THE 21ST CENTURY





# KEY TECHNOLOGY ENABLERS FOR THE EVOLVING THREAT SPACE

21<sup>ST</sup> CENTURY STRATEGIC TECHNOLOGY VECTORS

## Preparing Human Terrain

- **Social/cultural dynamics modeling**
- **Automated language processing**
- **Rapid training/learning methods/aids**

## Ubiquitous Observation

- **Day/night all-weather wide area surveillance**
- **Close-in sensor and tagging systems**
- **Soldiers-as-sensors**

## Contextual Exploitation

- **Mega-scale data management**
- **Situation dependent info extraction**
- **Human/system collaboration**

## Scalable Effects Delivery

- **Consequence-modeled decision making**
- **Information ops**
- **Time critical fires**
- **WMD mitigation**

# KEY TECHNOLOGY ENABLERS FOR THE EVOLVING THREAT SPACE

21<sup>ST</sup> CENTURY STRATEGIC TECHNOLOGY VECTORS

**Algorithmically  
and  
Computationally  
Rich**

- **Social/cultural dynamics modeling**
- **Automated language processing**
- **Rapid training/learning methods/aids**
- **Day/night all-weather wide area surveillance**
- **Close-in sensor and tagging systems**
- **Soldiers-as-sensors**
- **Mega-scale data management**
- **Situation dependent info extraction**
- **Human/system collaboration**
- **Consequence-modeled decision making**
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- **Time critical fires**
- **WMD mitigation**

More Aggressive  
Threats



Adaptive and Intelligent  
Data-Fused Sensors

- Threats are more dynamic and in deeper hide (collapsing time lines)
- System performance is outpaced by changing threat environments
- Cooperative battle management requires robust information backbone

Sensor Data Flow  
Overwhelming Human Analyst



Cognitive Information  
Exploitation

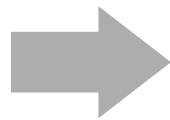
- Sensor bandwidth is increasing faster than processor capability
- Target classification has become a multi sensor

# Computer: Yesterday and Today



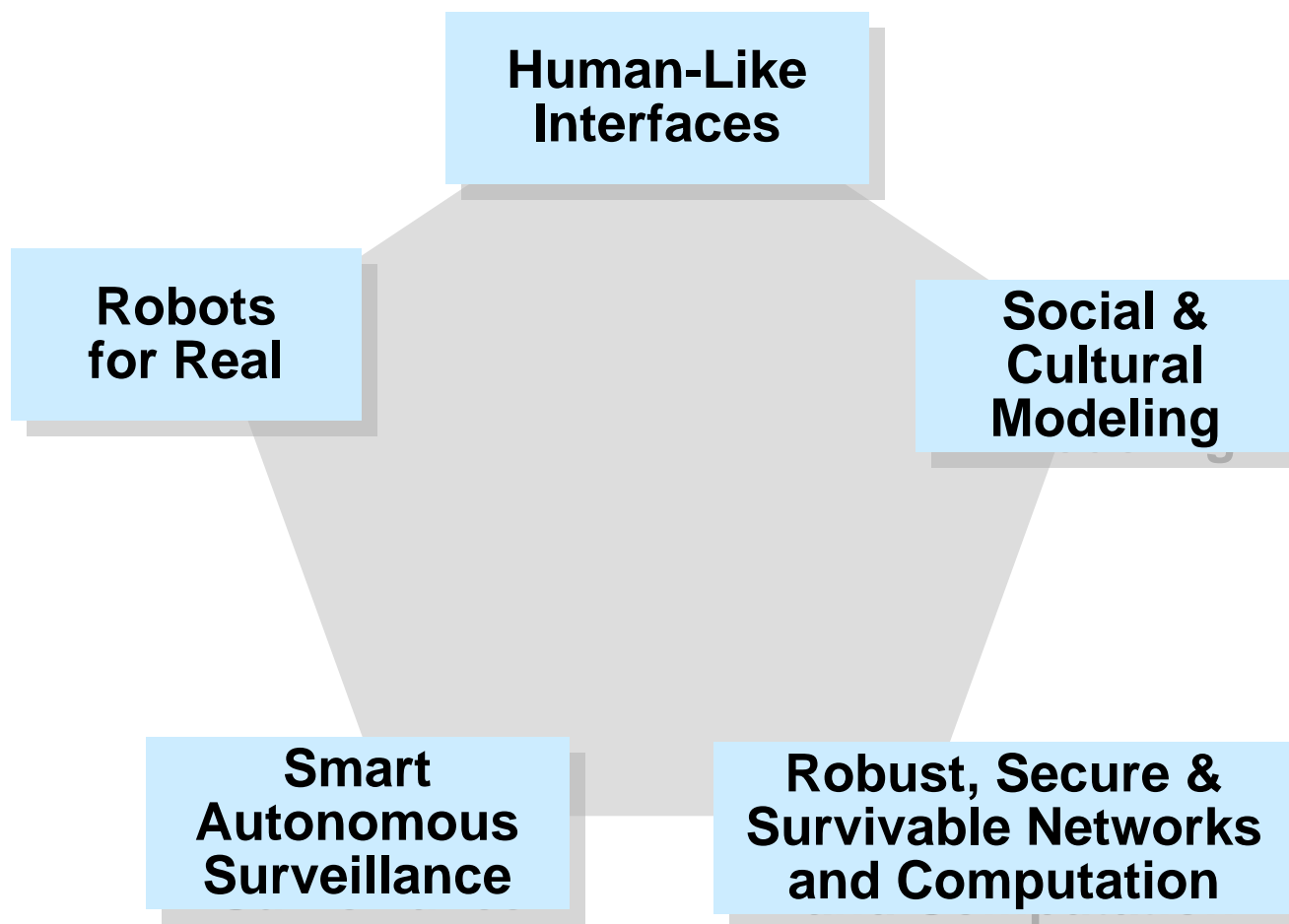
- Computation of static functions in a static environment, with well-understood specification
- Computation is its main goal
- Single agent
- Batch processing of text and homogeneous data
- Stand-alone applications
- Binary notion of correctness
- Adaptive systems operating in environments that are dynamic and uncertain
- Communication, sensing, and control just as important
- Multiple agents that may be cooperative, neutral, adversarial
- Stream processing of massive, heterogeneous data
- Interaction with humans is key
- Trade off multiple criteria

**Today's World**



**Ubiquitous communication,  
cheap computation,  
overwhelming data, and  
scarce human resource**

# Technology Research Challenges



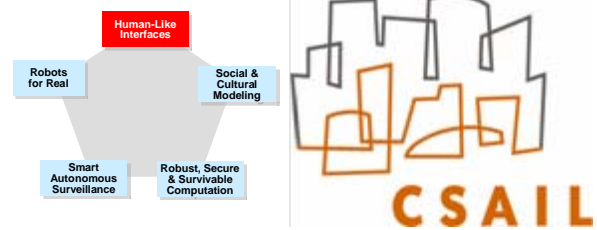
## Environment

High tempo  
Enormous data loads  
Civilian clutter  
Deep hide threats

Wicked problems  
Unstructured environments  
Cultural interaction  
High consequence



# Challenge 1: *Human-like Interfaces*

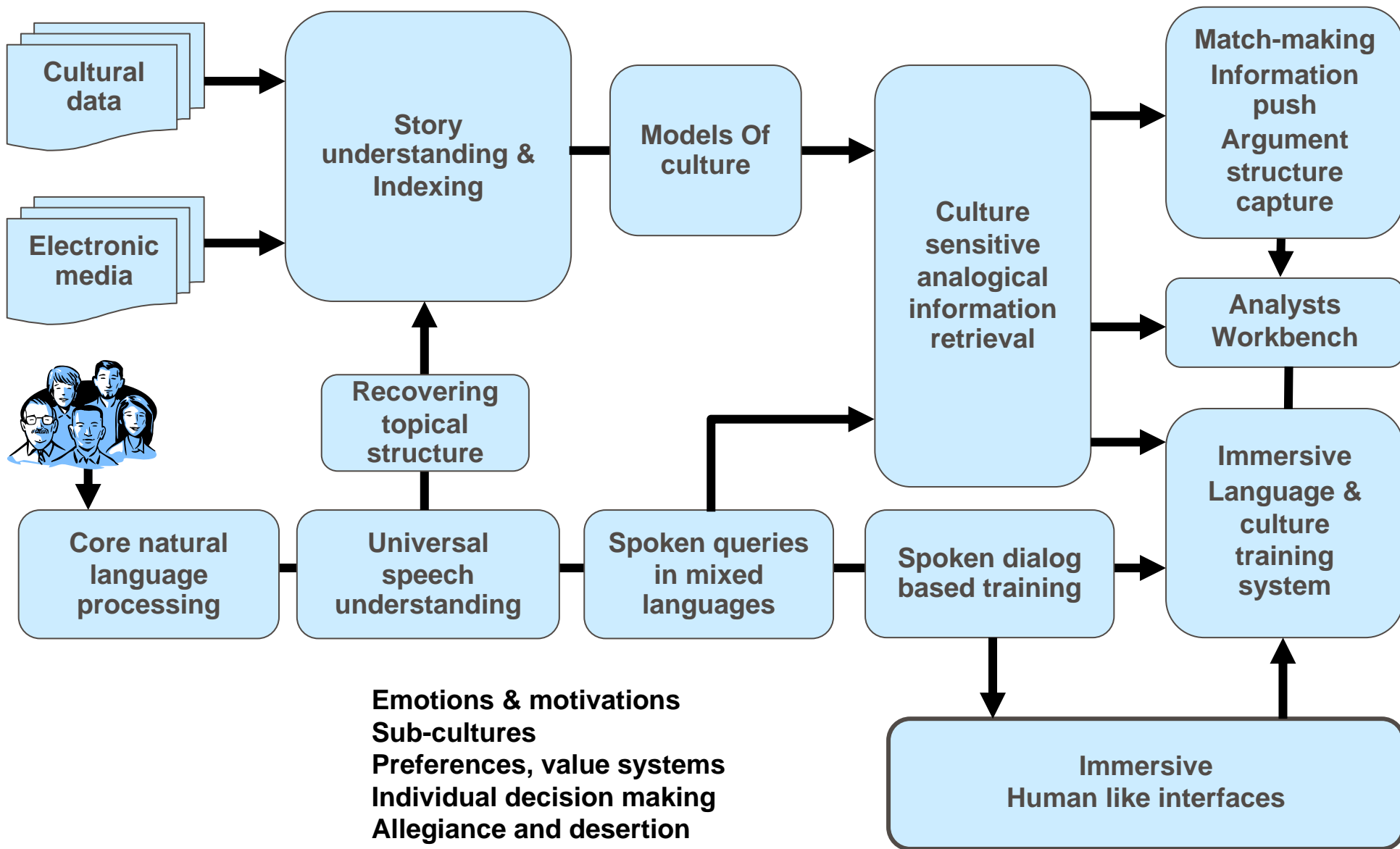
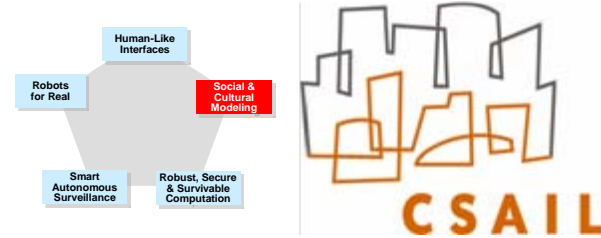


- Interacting with computation should be as natural as interacting with people.

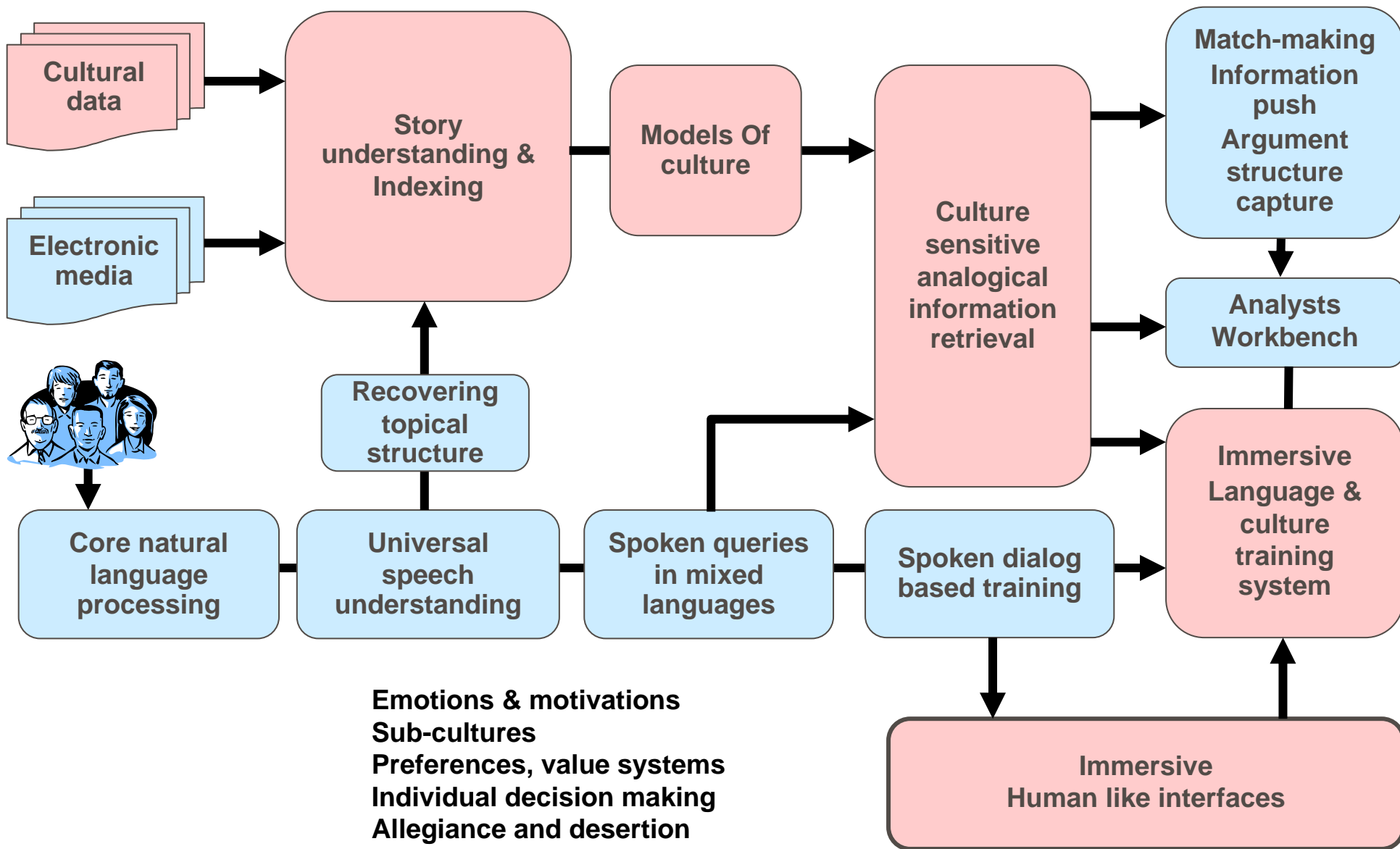
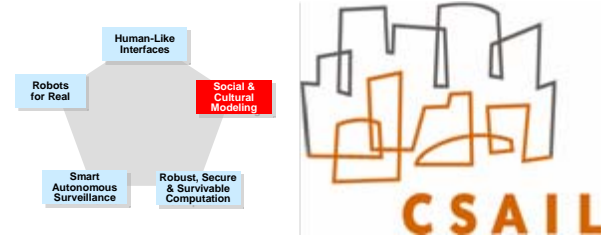


- **Human-like interfaces need to be:**
  - modality-opportunistic
  - modality-agnostic
  - non-distracting
  - symmetrically-multimodal
  - mixed-initiative
  - multi-lingual

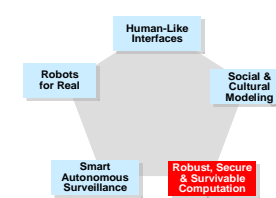
# Challenge 2: Operate in Foreign Cultures and Coalitions



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# Challenge 3: Make Net-Centric Systems Secure and Survivable

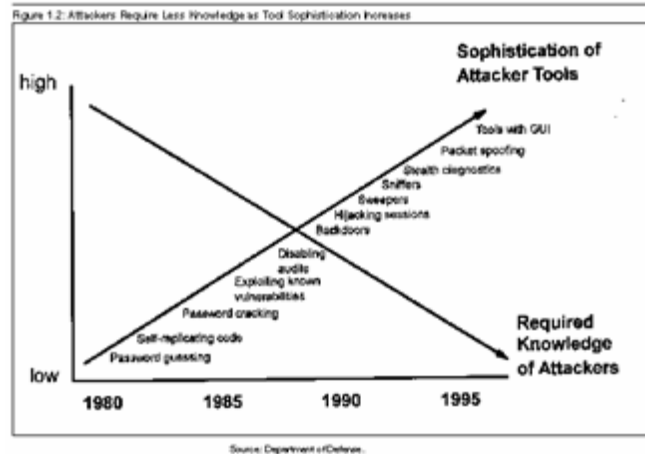
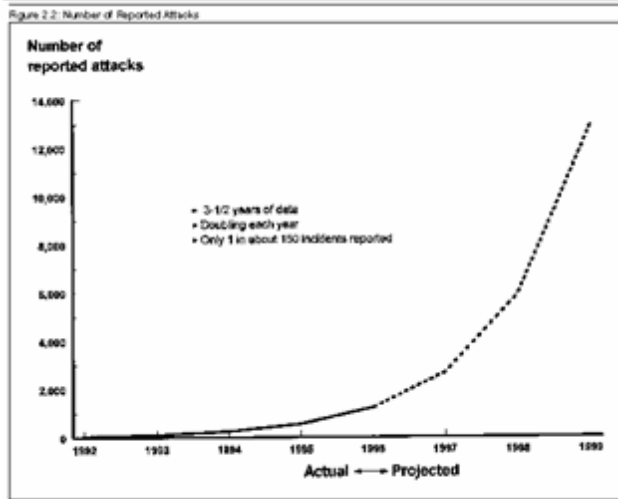


Capable and dedicated opponents

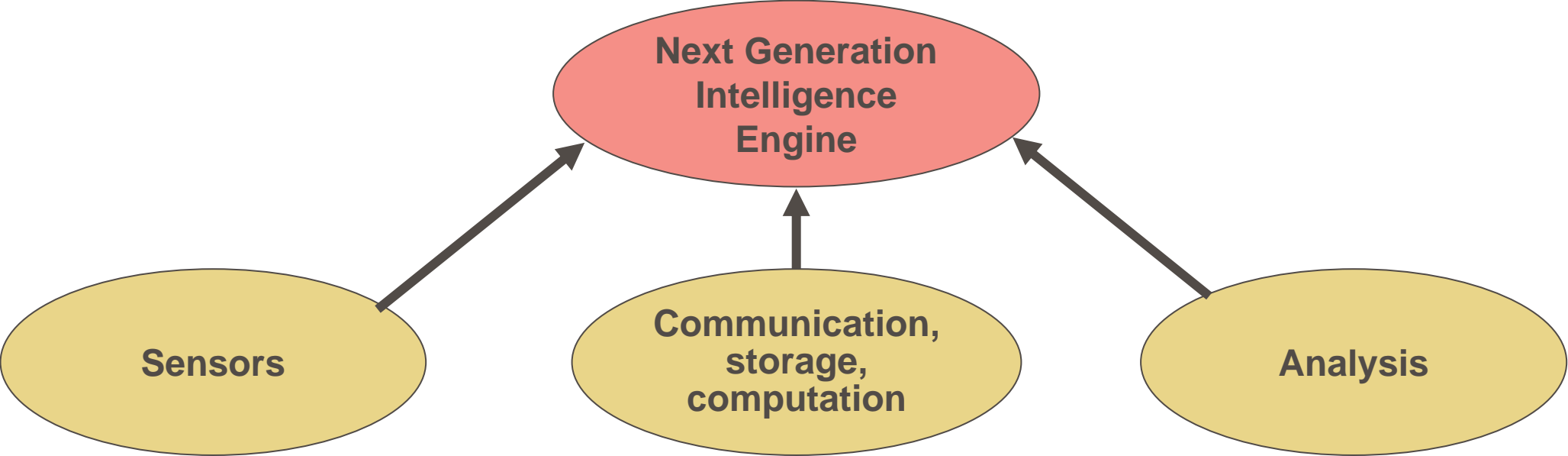
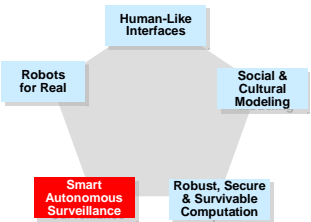
Mobile and distributed components



Heterogeneous systems



# Challenge 4: Smart Autonomous Surveillance

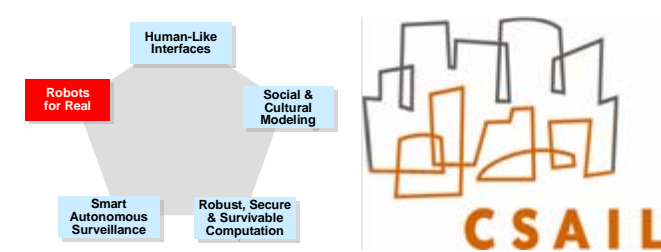


- Computational cameras
- Coded aperture sensors
- Queuing sensors

- Power and content-aware networking.
- Fusion across modality, time, place, and source

- Change detection
- anomaly alerts
- contextual analysis, integration with historical data,
- **prediction**

# Challenge 5: Robotics for Real



- **Military “robots” today lack autonomy**
  - Currently, many soldiers operate one robot
  - Want few soldiers working with a *team* of *agile* robots, to achieve *force multiplication* even in *harsh* environments
  - Put fewer soldiers in harm’s way
- **Better robots for monitoring**
  - *Enable* soldiers w/ persistent and pervasive ISR, including from hard to reach places (e.g., inside buildings/caves/bunker networks)
- **Better robots for logistics**
  - *Replace* soldiers in the supply chain with capable autonomous robots and vehicles

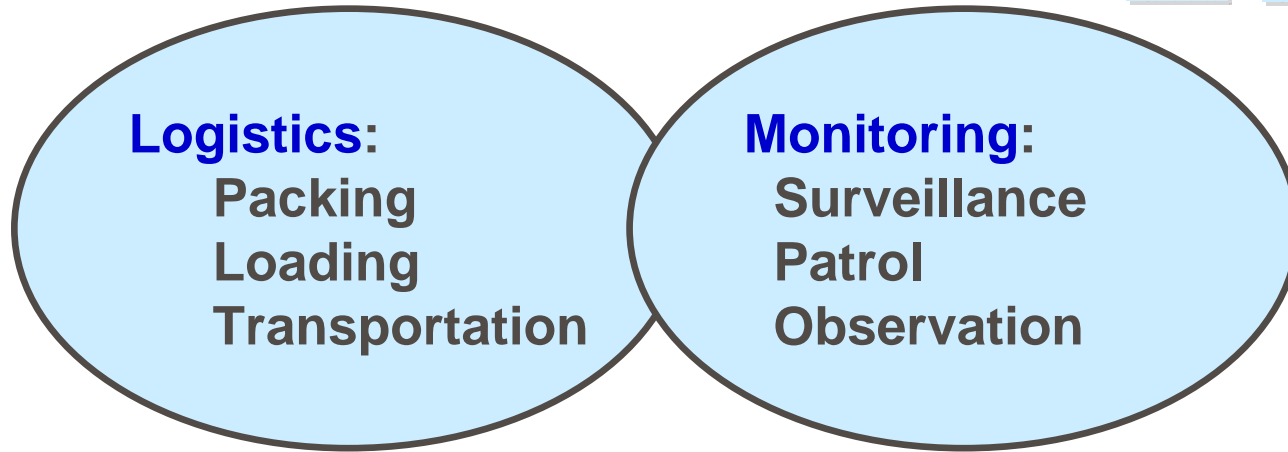
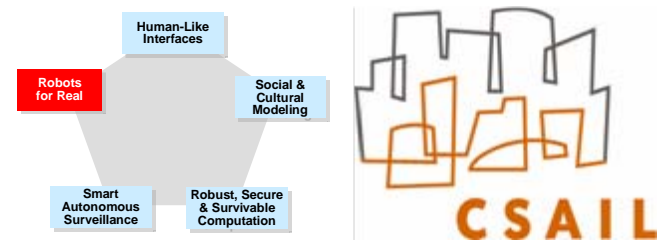


RQ1-Predator GCS



Supply-chain task

# Key Research Elements



**Perception and Awareness**

**Planning and Reasoning**

**Manipulation and Control**

**Communication and Coordination**

Vision  
Speech  
Gesture  
Localization  
Surround awareness

Uncertainty  
Dynamic world  
Scale  
Prediction

Grasping  
Rolling, legged,  
flying mobility

Teaming  
Coordinated motion

← **Enabling Technical Areas** →

# 10 year Vision: Exploiting Algorithms and Computation in Human-Like Ways



## Human-like Interfaces

multimodal interaction

uncontrolled environments

learn new vocabulary by example

adapting opportunistically to modalities available

*non-distracting interaction with a teammate*

## Social & Cultural Operations

Robust understanding of causal structures

Continuously evolving models of culture, values, motivations, preferences

**Full dialogue**

**Immersive, story and dialogue based interactions**

## Secure and Survivable Systems

Systematic survivability, defense in depth

Auditable assurance cases, formal methods and self-checking software and hardware together

**High confidence that failures and security attacks have not and will not occur**

## Autonomous Robotics

Autonomous vehicles require minimal supervision, and outperform the best human pilots

Robotic supply chain improves efficiency and surge response, greatly reducing the danger to humans

**Humans interact with robots as partners and capable teammates**

## Smart Autonomous Surveillance

Computational cameras

Queuing sensors

Change detection

Power and content-aware networking.

Fusion across modality, time, place, and source

contextual analysis, integration with historical data

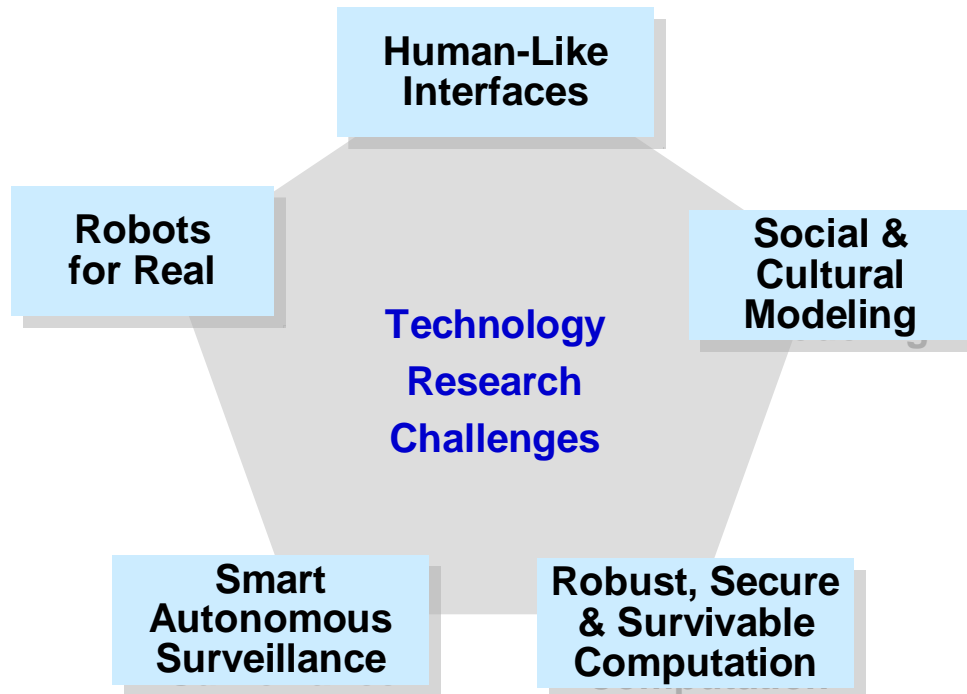
**prediction**

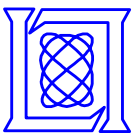




# Summary

- We are in a much more challenging threat environment
- Success will depend on operating;
  - in high tempo unstructured environments
  - against asymmetric adversaries in deep civilian hide
- A new set of research challenges are before us:





# The Power of a New Initiative

## The New York Times

**October 9, 1903**

“The flying machine which will really fly might be evolved by the combined and continuous efforts of mathematicians and mechanics in from one million to ten million years”

“We started assembly today”

**Orville Wright's Diary  
October 9, 1903**



**December 17, 1903**