

# 2D-3D Registration of Optical and Ladar Imagery for Real-Time Tracking

Andrew Mastin,<sup>1,2</sup> Jeremy Kepner,<sup>1</sup> John Fisher III<sup>2</sup> <sup>1</sup>Lincoln Laboratory

<sup>2</sup>Computer Science and Artificial Intelligence Laboratory Massachusetts Institute of Technology, Cambridge MA 02139 mastin@csail.mit.edu kepner@ll.mit.edu fisher@csail.mit.edu

#### High Performance Embedded Computing (HPEC) Workshop

#### 23-25 September 2008

This work is sponsored in part by the Department of the Air Force under Air Force contract FA8721-05-C-0002. Opinions, interpretations, conclusions and recommendations are those of the author and not necessarily endorsed by the United States Government.





## Overview



#### UAV with on-board 3D ladar imagery







Initial ladar-optical registration with feature detection and statistical registration



Registration updated by tracking feature points in video

Real-time tracking with occlusion reasoning from ladar imagery



- Commonly used for registration of multi-modal medical imagery
- Information theoretic similarity measure with optimization
- Machine learning approach





## **Fusion of Optical and Ladar Imagery**



ladar\_drape\_demo.avi